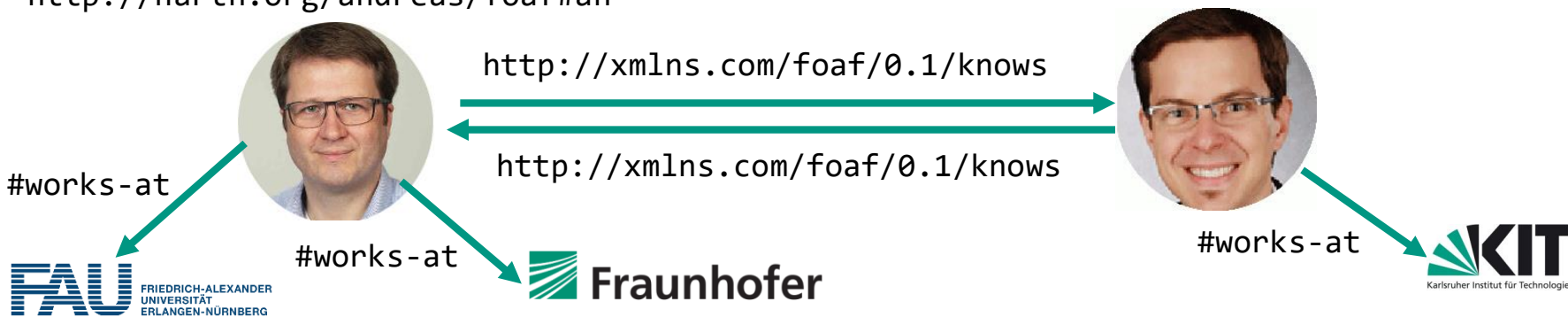


Tutorial on Distributed Knowledge Graphs for the Web of Things, Part VII: Executing RW Linked Data Agents

Tobias Käfer (KIT) and Andreas Harth (FAU)

Tutorial @ 10th International Conference on the Internet of Things (IoT), 2020

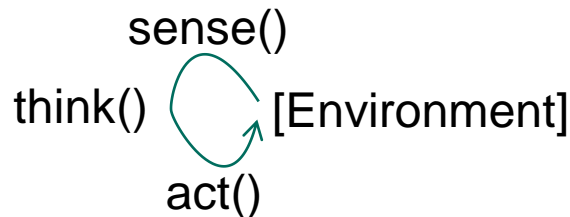
<http://harth.org/andreas/foaf#ah>



How Far Away Are We From AI Agents on the Web of Things?

- Cognitive loop:
 - while true:
 - sense()
 - think()
 - act()
- Read-Write Linked Data gives us:
 - sense() and act() to interact with distributed sources
 - Knowledge Graphs to describe data

Russell / Norvig's Agent Layer Cake [1]	Ingredients
Agents with goals	Capability descriptions
Agents with internal state	State Maintenance
Simple reflex agents	Execution semantics
(Describe Perception)	Data model
(Perception/action means)	Interaction



[1] Russell and Norvig: "Artificial Intelligence – A Modern Approach". Prentice Hall (1995).

Technologies Covered So Far

- Read-Write Linked Data processing with IoT Devices
- Web of Things

Level	Foundational approaches / categories						
Capability description	Input, Output, Precondition, Effect (for automated composition)			Affordance (for manual composition)			...
Composition description	Rules	BPEL*	Pi calculus	Petri Nets	(Temporal) logic	Unformalised Implementation	...
Execution Semantics	ASM		LTS		Situation Calculus	Unformalised Implementation	...
Data model	Graph (RDF)				Nested (JSON, XML)		...
Interaction	REST		Arbitrary functions		Event/push	Blackboard	...

*Semantics of BPEL have been given eg. in Petri Nets and ASMs, but Petri Nets are also used to describe compositions

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Technologies Covered So Far

IoT Platforms

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OWL-S and WSMO

■ Semantic Web Service Description Language Stacks

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Hydra and Schema.org Potential Actions

- Affordance descriptions
- cf. Web of Things Actions/Properties/Events

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RESTdesc [1]

- Aim: Automated service composition and composition execution in the presence of hyperlinks in HTTP responses

- Composition problem:

- Initial knowledge

`<#r> :isOn false .`

- API descriptions:

`{ preconditions }=>{ HTTP-request.postconditions }.`

- Precondition, Postcondition: ~ BGP; Postcondition ~ HTTP response's body
- HTTP-Request: (Method, URI + optional parameters)
 - Optional: eg. body: URIs or literals

- Goal specification

`{ <#r> :isOn true }=>{<#r> :isOn true } .`

- Background knowledge, eg. ontologies

- Sample API description:

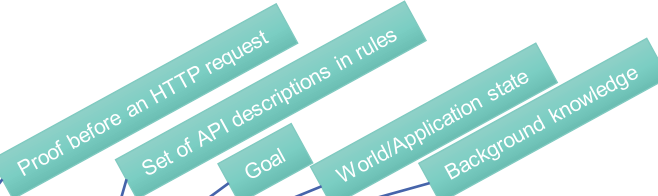
`@prefix : <http://example.org/>.`

`@prefix http: <http://www.w3.org/2011/http#>.`

```
{
  <#r> :isOn false .
}
=>
{
  _:request http:methodName "PUT";
    http:requestURI /relay/1 ;
    http:body "<#r> :isOn true ."
    http:resp [ http:body ?b1 ].
  <#r> :isOn true .
}
```

[1] Verborgh, Steiner, Van Deursen, Coppens, Vallés, Van de Walle: "Functional descriptions as the bridge between hypermedia APIs and the Semantic Web". In Proc. 3rd International Workshop on RESTful Design (WS-REST) (2012)

RESTdesc Algorithm [1]



- 1) Start an N3 reasoner to generate a pre-proof for (R, g, H, B) .
 - a) If the reasoner is not able to generate a proof, halt with failure.
 - b) Else scan the pre-proof for applications of rules of R , set the number of these applications to n_{pre}
- 2) Check n_{pre} :
 - a) If $n_{pre} = 0$, halt with success.
 - b) Else continue with 3).
- 3) Out of the pre-proof, select a sufficiently specified HTTP request description which is part of the application of a rule $r \in R$.
- 4) Execute the described HTTP request and parse the (possibly empty) server response to a set of ground formulas G .
- 5) Invoke the reasoner with the new API composition problem $(R, g, H \cup G, B)$ to produce a post-proof.
- 6) Determine n_{post} :
 - a) If the reasoner was not able to generate a proof, set $n_{post} := n_{pre}$.
 - b) Else scan the proof for the number of inference steps which are using rules from R and set this number of steps to n_{post} .
- 7) Compare n_{post} with n_{pre} :
 - a) If $n_{post} \geq n_{pre}$, go back to 1) with the new API composition problem $(R \setminus \{r\}, g, H, B)$.
 - b) If $n_{post} < n_{pre}$, the post-proof can be used as the next pre-proof. Set $n_{pre} := n_{post}$ and continue with 2)

[1] Verborgh, Arndt, Van Hoescke, De Roo, Mels, Steiner, Gabarró: "The pragmatic proof: Hypermedia API composition and execution". *Theory and Practice of Logic Programming*, 17(1), (2017)

Classifying RESTdesc

More than mere affordances, but not full IOPE

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ASM4LD [0]

- A Model of Computation for Read-Write Linked Data [0]
- Operational Semantics for the Linked Data-Fu Language [1]

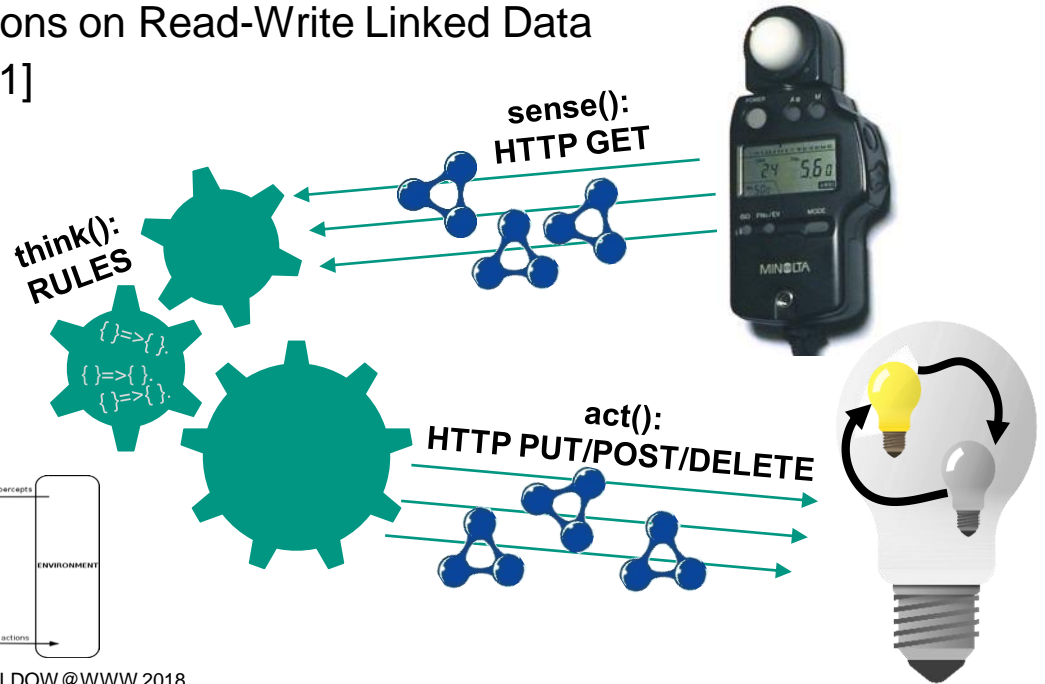
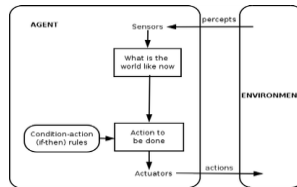
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[0] Käfer & Harth: Rule-based Programming of User Agents for Linked Data. LDOW@WWW, 2018

[1] Stadtmüller, Speiser, Harth, Studer: Data-Fu: a language and an interpreter for interaction with read/write linked data. WWW 2013

ASM4LD [0]

- Aim: Execution of agent specifications on Read-Write Linked Data
- Inspired by Simple Reflex Agents [1]
- Based on:
 - Abstract State Machines [2]
 - Model-theoretic semantics of RDF
 - Message semantics of HTTP
- Cognitive loop
 - + Fixpoint loop for reasoning
 - + Fixpoint loop for link following



[0] Käfer & Harth: Rule-based Programming of User Agents for Linked Data. LDOW@WWW 2018

[1] Russell & Norvig: Artificial Intelligence – A Modern Approach. Prentice Hall (1996)

[2] Gurevich.: "Evolving algebras 1993: Lipari guide." *Specification and validation methods* (1995)

Require: assertions ▷ Graph

Require: rules ▷ Derivation and request rules

var data, oldData: set<triple>

var fixpointReached: Boolean

var unsafeRequests: set<request>

while true **do** ▷ Loop of the ASM steps

 unsafeRequests.clear()

 data.clear()

 data.add(assertions)

repeat ▷ Loop for determining the fixpoint and the update set

 fixpointReached <- true

for rule : rules **do**

if rule.matches(data) **then**

 oldData = data.copy()

if rule.type==derivation **then**

 data.add(rule.match(data).data)

else ▷ So the rule must be an interaction rule

if rule.match(data).request.type==GET **then**

 data.add(rule.match(data).request.execute())

else

 unsafeRequests.add(rule.match(data).request)

end if

end if

if ! data.copy().remove(oldData).isEmpty() **then**

 fixpointReached <- false

end if

end if

end for

until fixpointReached

for request : unsafeRequests **do** ▷ Enacting the update set

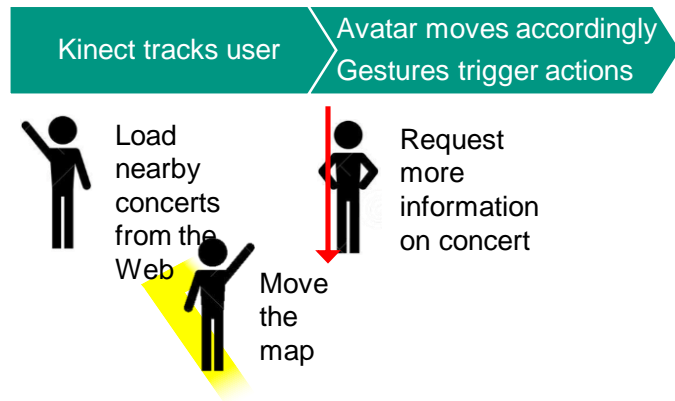
 request.execute()

end for

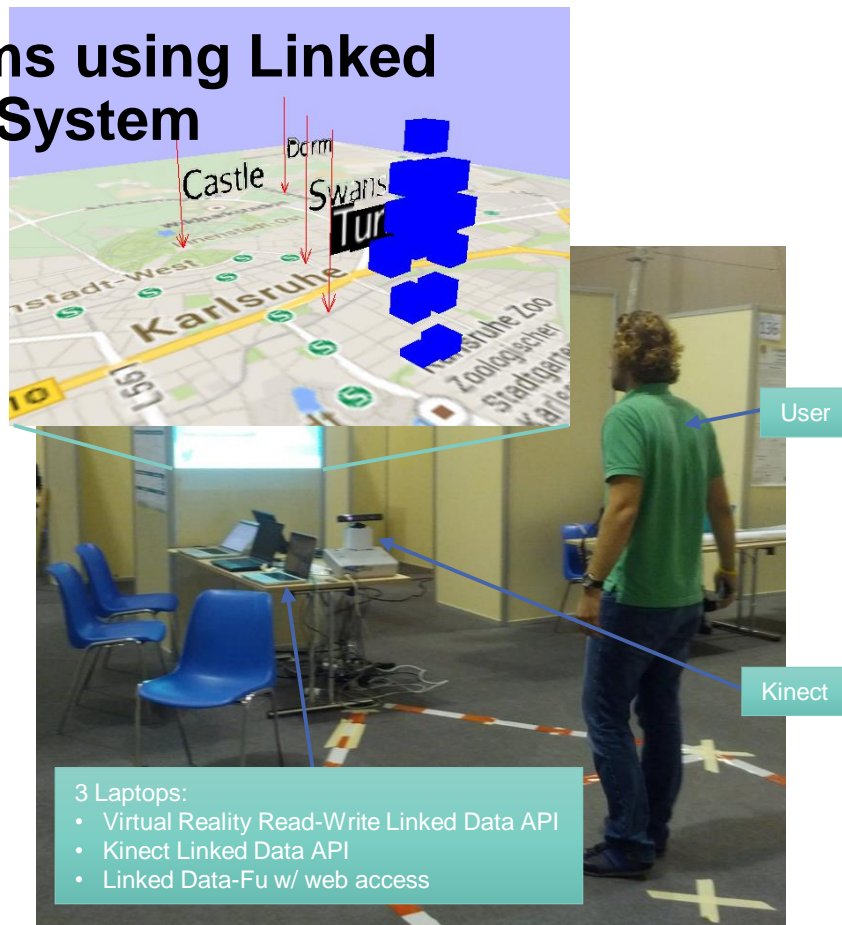
end while

**Algorithm to combine
fixpoint calculation for
forward-chaining reasoning,
and link following,
with the cognitive loop**

Integration of Distributed Systems using Linked Data: Example: a Virtual Reality System



- We encoded in Linked Data-Fu rules:
 - Movement of the avatar according to Kinect data
 - Detection of user gestures
 - Movement of the map according to gestures
 - Loading of concert data from the web
 - Data integration between VR RWLD API, concert LD API, Kinect LD API
- Execution at Kinect sensor refresh rate (30Hz)



Keppmann, Käfer, Stadtmüller, Schubotz, Harth: "High Performance Linked Data Processing for Virtual Reality Environments". P&D ISWC 2014.

Video: Manufacturing Control (2020)

